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APPROVED BY
Frontiers Editorial Office,
Frontiers Media SA, Switzerland

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RECEIVED 22 October 2025

ACCEPTED 27 October 2025

PUBLISHED 06 November 2025

CITATION

Chen J, Chen M, Wang J, Mao Q, Xie F and Dames P (2025) Correction: Distributed multi-robot active gathering for non-uniform agriculture and forestry information. *Front. Plant Sci.* 16:1730134. doi: 10.3389/fpls.2025.1730134

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Correction: Distributed multi-robot active gathering for non-uniform agriculture and forestry information

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KEYWORDS

multi-robot systems, active information gathering, Thompson sampling, multi-target tracking, distributed control

A Correction on

Distributed multi-robot active gathering for non-uniform agriculture and forestry information

By Chen J, Chen M, Wang J, Mao Q, Xie F and Dames P (2025) *Front. Plant Sci.* 16:1699124. doi: 10.3389/fpls.2025.1699124

The title of this article was erroneously given as “Distributed multi-robot active gathering for non-uniform agriculture and forestry information multi-robot active gathering”. The correct title of the article is “Distributed multi-robot active gathering for non-uniform agriculture and forestry information”.

The original version of this article has been updated.

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